NCPC 2017 Presentation of solutions

The Jury

2017-10-07

NCPC 2017 solutions

NCPC 2017 Jury

- Per Austrin (KTH Royal Institute of Technology)
- Pål Grønås Drange (Statoil ASA)
- Markus Fanebust Dregi (Statoil ASA/Webstep)
- Antti Laaksonen (CSES)
- Ulf Lundström (Excillum)
- Jimmy Mårdell (Spotify)
- Lukáš Poláček (Google)
- Johan Sannemo (Google)
- Pehr Söderman (Kattis)

J — Judging Moose

Problem

Classify moose based on their horns.

Some solution (guess the language)

```
solve(0, 0) :-
    !, write('Not a moose').
solve(L, R) :-
    type(L, R, Type),
    Val is 2*max(L, R),
    write(Type), write(' '), write(Val).
type(L, L, "Even") :- !.
type(_, _, "Odd").
```

Statistics: 347 submissions, 252 accepted, first after 00:03

Pick best relay team, given runners' standing and flying start times.

Solution

Pre-sort runners by their flying start time

Pick best relay team, given runners' standing and flying start times.

- Pre-sort runners by their flying start time
- 2 Try every runner on the first leg

Pick best relay team, given runners' standing and flying start times.

- Pre-sort runners by their flying start time
- Iry every runner on the first leg
- So For every choice, fill up with 3 fastest remaining flying start runners

Pick best relay team, given runners' standing and flying start times.

Solution

- Pre-sort runners by their flying start time
- Iry every runner on the first leg
- So For every choice, fill up with 3 fastest remaining flying start runners

Complexity is $O(n \log n)$. Many other solutions are also possible.

Pick best relay team, given runners' standing and flying start times.

Solution

- Pre-sort runners by their flying start time
- O Try every runner on the first leg
- Sor every choice, fill up with 3 fastest remaining flying start runners

Complexity is $O(n \log n)$. Many other solutions are also possible.

Statistics: 491 submissions, 189 accepted, first after 00:08

Problem

There are n teams who solve m problems in an ICPC style programming contest. After each successful submission, print the rank of your team.

Solution

• Maintain a set S: the teams whose score is better than your team's score. Your rank is |S| + 1.

Problem

There are n teams who solve m problems in an ICPC style programming contest. After each successful submission, print the rank of your team.

- Maintain a set S: the teams whose score is better than your team's score. Your rank is |S| + 1.
- When your team solves a problem, remove all teams with a worse score from S.

Problem

There are n teams who solve m problems in an ICPC style programming contest. After each successful submission, print the rank of your team.

- Maintain a set S: the teams whose score is better than your team's score. Your rank is |S| + 1.
- When your team solves a problem, remove all teams with a worse score from S.
- When another team solves a problem, add it to S if its score becomes better than your team's score.

Problem

There are n teams who solve m problems in an ICPC style programming contest. After each successful submission, print the rank of your team.

Solution

- Maintain a set S: the teams whose score is better than your team's score. Your rank is |S| + 1.
- When your team solves a problem, remove all teams with a worse score from S.
- When another team solves a problem, add it to S if its score becomes better than your team's score.

The *amortized* complexity of both operations is $O(\log n)$.

Problem

There are n teams who solve m problems in an ICPC style programming contest. After each successful submission, print the rank of your team.

Solution

- Maintain a set S: the teams whose score is better than your team's score. Your rank is |S| + 1.
- When your team solves a problem, remove all teams with a worse score from S.
- When another team solves a problem, add it to S if its score becomes better than your team's score.

The *amortized* complexity of both operations is $O(\log n)$.

Statistics: 578 submissions, 79 accepted, first after 00:29

The dependencies form a directed graph, and the task is to find a shortest cycle in a directed graph.

Solution

 ${\small \bullet}$ Use the Floyd–Warshall all pairs shortest path algorithm with diagonals initialized to ∞

The dependencies form a directed graph, and the task is to find a shortest cycle in a directed graph.

- ${\small \bullet}$ Use the Floyd–Warshall all pairs shortest path algorithm with diagonals initialized to ∞
- 2 Afterwards diagonal entry d(u, u) gives length of shortest cycle passing through u.

The dependencies form a directed graph, and the task is to find a shortest cycle in a directed graph.

- ${\small \bullet}$ Use the Floyd–Warshall all pairs shortest path algorithm with diagonals initialized to ∞
- 2 Afterwards diagonal entry d(u, u) gives length of shortest cycle passing through u.
- Seconstruct shortest cycle using the distance matrix.

The dependencies form a directed graph, and the task is to find a shortest cycle in a directed graph.

- ${\small \bullet}$ Use the Floyd–Warshall all pairs shortest path algorithm with diagonals initialized to ∞
- 2 Afterwards diagonal entry d(u, u) gives length of shortest cycle passing through u.
- Seconstruct shortest cycle using the distance matrix.
- Alternatively, run BFS from each vertex v to find shortest v-v cycle.

The dependencies form a directed graph, and the task is to find a shortest cycle in a directed graph.

Solution

- ${\small \bullet}$ Use the Floyd–Warshall all pairs shortest path algorithm with diagonals initialized to ∞
- 2 Afterwards diagonal entry d(u, u) gives length of shortest cycle passing through u.
- Seconstruct shortest cycle using the distance matrix.
- Alternatively, run BFS from each vertex v to find shortest v-v cycle.

Complexity is $O(n^3)$ or O(n(n+m)).

The dependencies form a directed graph, and the task is to find a shortest cycle in a directed graph.

Solution

- ${\small \bullet}$ Use the Floyd–Warshall all pairs shortest path algorithm with diagonals initialized to ∞
- 2 Afterwards diagonal entry d(u, u) gives length of shortest cycle passing through u.
- 3 Reconstruct shortest cycle using the distance matrix.
- Alternatively, run BFS from each vertex v to find shortest v-v cycle.

Complexity is $O(n^3)$ or O(n(n+m)).

Statistics: 290 submissions, 52 accepted, first after 00:30

E — Emptying the Baltic

Problem

How much water can we drain from a point at the bottom of the sea?

E — Emptying the Baltic

Problem

How much water can we drain from a point at the bottom of the sea?

Solution

Similar to Dijkstra's or Prim's algorithms:

How much water can we drain from a point at the bottom of the sea?

- Similar to Dijkstra's or Prim's algorithms:
 - Keep track of *tentative* depth of each square upper bound on the final water level.

How much water can we drain from a point at the bottom of the sea?

Solution

Similar to Dijkstra's or Prim's algorithms:

- Keep track of *tentative* depth of each square upper bound on the final water level.
- 2 At the start, only the drainage point has known depth.

How much water can we drain from a point at the bottom of the sea?

Solution

Similar to Dijkstra's or Prim's algorithms:

- Keep track of *tentative* depth of each square upper bound on the final water level.
- 2 At the start, only the drainage point has known depth.
- In each iteration, pick the square s with the lowest tentative depth and mark it *final*. Update tentative depth of all neighbours of s.

How much water can we drain from a point at the bottom of the sea?

Solution

Similar to Dijkstra's or Prim's algorithms:

- Keep track of *tentative* depth of each square upper bound on the final water level.
- 2 At the start, only the drainage point has known depth.
- In each iteration, pick the square s with the lowest tentative depth and mark it *final*. Update tentative depth of all neighbours of s.

Time complexity is $O(n \log n)$, where $n = w \cdot h$ is the size of the grid.

How much water can we drain from a point at the bottom of the sea?

Solution

Similar to Dijkstra's or Prim's algorithms:

- Keep track of *tentative* depth of each square upper bound on the final water level.
- 2 At the start, only the drainage point has known depth.
- In each iteration, pick the square s with the lowest tentative depth and mark it *final*. Update tentative depth of all neighbours of s.

Time complexity is $O(n \log n)$, where $n = w \cdot h$ is the size of the grid.

Statistics: 296 submissions, 55 accepted, first after 00:47

Given n bit vectors of length k, find a bit vector whose minimum Hamming distance is maximum.

Solution

• There are a total of 2^k possible bit vectors.

Given n bit vectors of length k, find a bit vector whose minimum Hamming distance is maximum.

- There are a total of 2^k possible bit vectors.
- Create a graph where each node is a bit vector and there is an edge between two nodes if they differ in a single bit.
 (aka the k-dimensional hypercube graph)

Given n bit vectors of length k, find a bit vector whose minimum Hamming distance is maximum.

- There are a total of 2^k possible bit vectors.
- Create a graph where each node is a bit vector and there is an edge between two nodes if they differ in a single bit.
 (aka the k-dimensional hypercube graph)
- Use a single BFS with the n given vectors as sources to find the node whose minimum distance is maximum.

Given n bit vectors of length k, find a bit vector whose minimum Hamming distance is maximum.

Solution

- There are a total of 2^k possible bit vectors.
- Create a graph where each node is a bit vector and there is an edge between two nodes if they differ in a single bit.
 (aka the k-dimensional hypercube graph)
- Use a single BFS with the n given vectors as sources to find the node whose minimum distance is maximum.

Time complexity is $O(n + k \cdot 2^k)$

Given n bit vectors of length k, find a bit vector whose minimum Hamming distance is maximum.

Solution

- There are a total of 2^k possible bit vectors.
- Create a graph where each node is a bit vector and there is an edge between two nodes if they differ in a single bit.
 (aka the k-dimensional hypercube graph)
- Use a single BFS with the n given vectors as sources to find the node whose minimum distance is maximum.

Time complexity is $O(n + k \cdot 2^k)$

Statistics: 461 submissions, 40 accepted, first after 00:17

Problem

Dynamically keep track of "uniqueness values" of cards while cards are being sold off.

Problem

Dynamically keep track of "uniqueness values" of cards while cards are being sold off.

Solution

When card is sold, at most 6 other cards (the 2 "adjacent" cards of each color) can change their uniqueness values.

Problem

Dynamically keep track of "uniqueness values" of cards while cards are being sold off.

- When card is sold, at most 6 other cards (the 2 "adjacent" cards of each color) can change their uniqueness values.
- ② For $c \in \{R, G, B\}$, keep set S_c of cards ordered by angle in color c.

Problem

Dynamically keep track of "uniqueness values" of cards while cards are being sold off.

- When card is sold, at most 6 other cards (the 2 "adjacent" cards of each color) can change their uniqueness values.
- ② For $c \in \{R, G, B\}$, keep set S_c of cards ordered by angle in color c.
- When selling card, find the ≤ 6 affected cards and recompute their uniqueness values, using fast lookup in the sets S_c .

Problem

Dynamically keep track of "uniqueness values" of cards while cards are being sold off.

- When card is sold, at most 6 other cards (the 2 "adjacent" cards of each color) can change their uniqueness values.
- ② For $c \in \{R, G, B\}$, keep set S_c of cards ordered by angle in color c.
- When selling card, find the ≤ 6 affected cards and recompute their uniqueness values, using fast lookup in the sets S_c .
- Keep all cards in another ordered set ordered by uniqueness value for fast extraction of next card to sell.

C — Compass Card Sales

Problem

Dynamically keep track of "uniqueness values" of cards while cards are being sold off.

Solution

- When card is sold, at most 6 other cards (the 2 "adjacent" cards of each color) can change their uniqueness values.
- Gervard For c ∈ {R, G, B}, keep set S_c of cards ordered by angle in color c.
- When selling card, find the ≤ 6 affected cards and recompute their uniqueness values, using fast lookup in the sets S_c .
- Keep all cards in another ordered set ordered by uniqueness value for fast extraction of next card to sell.

Complexity is $O(n \log n)$ with balanced search trees or similar.

C — Compass Card Sales

Problem

Dynamically keep track of "uniqueness values" of cards while cards are being sold off.

Solution

- When card is sold, at most 6 other cards (the 2 "adjacent" cards of each color) can change their uniqueness values.
- ② For $c \in \{R, G, B\}$, keep set S_c of cards ordered by angle in color c.
- When selling card, find the ≤ 6 affected cards and recompute their uniqueness values, using fast lookup in the sets S_c .
- Keep all cards in another ordered set ordered by uniqueness value for fast extraction of next card to sell.

Complexity is $O(n \log n)$ with balanced search trees or similar.

Statistics: 105 submissions, 14 accepted, first after 01:10

K — Kayaking

Problem

Assign pool of weak/normal/strong people to 2-person kayaks (of different speed factors) to maximize speed of slowest kayak.

Solution

K — Kayaking

Problem

Assign pool of weak/normal/strong people to 2-person kayaks (of different speed factors) to maximize speed of slowest kayak.

Solution

O Binary search over the answer.

K — Kayaking

Problem

Assign pool of weak/normal/strong people to 2-person kayaks (of different speed factors) to maximize speed of slowest kayak.

Solution

Binary search over the answer.

Check feasibility by greedily assigning people to kayaks

- kayaks requiring strong+strong or strong+normal get that
- kayaks that can handle weak+weak or weak+normal get that
- pair up remaining weaks with strongs and normals with normals and check if this can make all kayaks fast enough

Problem

Assign pool of weak/normal/strong people to 2-person kayaks (of different speed factors) to maximize speed of slowest kayak.

Solution

Binary search over the answer.

Check feasibility by greedily assigning people to kayaks

- kayaks requiring strong+strong or strong+normal get that
- kayaks that can handle weak+weak or weak+normal get that
- pair up remaining weaks with strongs and normals with normals and check if this can make all kayaks fast enough

Time complexity is $O(n \log n)$ for *n* people.

Problem

Assign pool of weak/normal/strong people to 2-person kayaks (of different speed factors) to maximize speed of slowest kayak.

Solution

Binary search over the answer.

Check feasibility by greedily assigning people to kayaks

- kayaks requiring strong+strong or strong+normal get that
- kayaks that can handle weak+weak or weak+normal get that
- pair up remaining weaks with strongs and normals with normals and check if this can make all kayaks fast enough

Time complexity is $O(n \log n)$ for *n* people.

Statistics: 82 submissions, 23 accepted, first after 00:46

Problem

Find fastest way of walking distance L. At certain points x_i we can choose to get a future temporary speedup (by buying a coffee), at the cost of cancelling any current speedup.

Solution

• Let S(i) be best time if we start from *i*'th cart.

Problem

Find fastest way of walking distance L. At certain points x_i we can choose to get a future temporary speedup (by buying a coffee), at the cost of cancelling any current speedup.

Solution



- Let S(i) be best time if we start from *i*'th cart.
- Easy dynamic programming: for each j > i, try buying next coffee at cart j

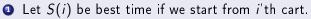
$$S(i) = \min_{j>i} S(j) + \text{Time to go from } x_i \text{ to } x_j$$

Problem

Find fastest way of walking distance L. At certain points x_i we can choose to get a future temporary speedup (by buying a coffee), at the cost of cancelling any current speedup.

Solution





Easy dynamic programming: for each j > i, try buying next coffee at cart j

$$S(i) = \min_{j>i} S(j) +$$
Time to go from x_i to x_j

3 Alas, leads to
$$\Omega(n^2)$$
 time – too slow!.

Problem

Find fastest way of walking distance L. At certain points x_i we can choose to get a future temporary speedup (by buying a coffee), at the cost of cancelling any current speedup.

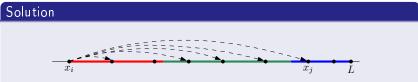
Solution



 From each x_i, three categories of choice for best next cart x_j: During cooldown, during drinking, and after finishing the coffee

Problem

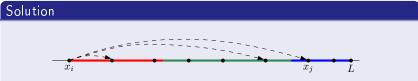
Find fastest way of walking distance L. At certain points x_i we can choose to get a future temporary speedup (by buying a coffee), at the cost of cancelling any current speedup.



- From each x_i, three categories of choice for best next cart x_j: During cooldown, during drinking, and after finishing the coffee
- Before/After drinking: best to pick smallest such j (get next coffee as soon as possible)

Problem

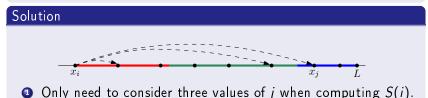
Find fastest way of walking distance L. At certain points x_i we can choose to get a future temporary speedup (by buying a coffee), at the cost of cancelling any current speedup.



- From each x_i, three categories of choice for best next cart x_j: During cooldown, during drinking, and after finishing the coffee
- Before/After drinking: best to pick smallest such j (get next coffee as soon as possible)
- During drinking: best to pick largest such j (keep drinking coffee as long as possible)

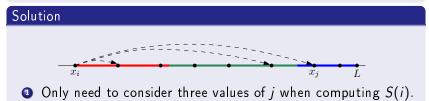
Problem

Find fastest way of walking distance L. At certain points x_i we can choose to get a future temporary speedup (by buying a coffee), at the cost of cancelling any current speedup.



Problem

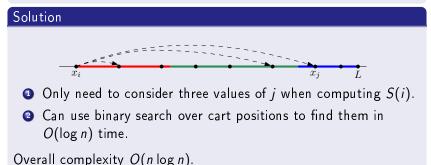
Find fastest way of walking distance L. At certain points x_i we can choose to get a future temporary speedup (by buying a coffee), at the cost of cancelling any current speedup.



Can use binary search over cart positions to find them in O(log n) time.

Problem

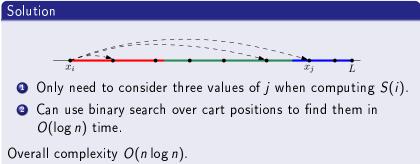
Find fastest way of walking distance L. At certain points x_i we can choose to get a future temporary speedup (by buying a coffee), at the cost of cancelling any current speedup.



(Exercise: can be improved to O(n) time.)

Problem

Find fastest way of walking distance L. At certain points x_i we can choose to get a future temporary speedup (by buying a coffee), at the cost of cancelling any current speedup.



(Exercise: can be improved to O(n) time.)

Statistics: 65 submissions, 7 accepted, first after 02:50

Problem

Given a set of rays from in 2D (0,0), and some points, assign max #points to a ray of minimum angular distance from the point, subject to ray capacities.

Problem

Given a set of rays from in 2D (0,0), and some points, assign max #points to a ray of minimum angular distance from the point, subject to ray capacities.

Phase 1

• Sort all rays and points by angle.

Problem

Given a set of rays from in 2D (0,0), and some points, assign max #points to a ray of minimum angular distance from the point, subject to ray capacities.

- Sort all rays and points by angle.
- For each point, compare distances to its two neighboring rays (Use sweep approach or binary search to find the two rays quickly)

Problem

Given a set of rays from in 2D (0,0), and some points, assign max #points to a ray of minimum angular distance from the point, subject to ray capacities.

- Sort all rays and points by angle.
- For each point, compare distances to its two neighboring rays (Use sweep approach or binary search to find the two rays quickly)
- Caveat! If using doubles, need to be careful with ϵ . (Turns out, distances can differ by $\approx 10^{-13}$ without being equal.)

Problem

Given a set of rays from in 2D (0,0), and some points, assign max #points to a ray of minimum angular distance from the point, subject to ray capacities.

- Sort all rays and points by angle.
- For each point, compare distances to its two neighboring rays (Use sweep approach or binary search to find the two rays quickly)
- Caveat! If using doubles, need to be careful with ϵ . (Turns out, distances can differ by $\approx 10^{-13}$ without being equal.)
- Can also check this using only integer computations. (But, despite small coordinates, need 64 bits.)

Problem

Given a set of rays from in 2D (0,0), and some points, assign max #points to a ray of minimum angular distance from the point, subject to ray capacities.

- Sort all rays and points by angle.
- For each point, compare distances to its two neighboring rays (Use sweep approach or binary search to find the two rays quickly)
- Caveat! If using doubles, need to be careful with ϵ . (Turns out, distances can differ by $\approx 10^{-13}$ without being equal.)
- Can also check this using only integer computations. (But, despite small coordinates, need 64 bits.)
- Points with a unique neighboring ray can be immediately assigned to that ray (if it has capacity left).

Problem

Given a set of rays from in 2D (0,0), and some points, assign max #points to a ray of minimum angular distance from the point, subject to ray capacities.

Phase 2

For remaining points (having two closest rays) we get a bipartite matching problem between points and rays.

Problem

Given a set of rays from in 2D (0,0), and some points, assign max #points to a ray of minimum angular distance from the point, subject to ray capacities.

- For remaining points (having two closest rays) we get a bipartite matching problem between points and rays.
- ② Graph is very simple (either a cycle, or a collection of paths)

Problem

Given a set of rays from in 2D (0,0), and some points, assign max #points to a ray of minimum angular distance from the point, subject to ray capacities.

- For remaining points (having two closest rays) we get a bipartite matching problem between points and rays.
- **2** Graph is very simple (either a cycle, or a collection of paths)
- Approach 1: solve using max flow (merging all points with the same angle into a single node with capacity = #points)

Problem

Given a set of rays from in 2D (0,0), and some points, assign max #points to a ray of minimum angular distance from the point, subject to ray capacities.

- For remaining points (having two closest rays) we get a bipartite matching problem between points and rays.
- **②** Graph is very simple (either a cycle, or a collection of paths)
- Approach 1: solve using max flow (merging all points with the same angle into a single node with capacity = #points)
 - Time complexity with Ford-Fulkerson is $O(p^2)$ where p is the number of train lines adjacent to some remaining person.

Problem

Given a set of rays from in 2D (0,0), and some points, assign max #points to a ray of minimum angular distance from the point, subject to ray capacities.

- For remaining points (having two closest rays) we get a bipartite matching problem between points and rays.
- ② Graph is very simple (either a cycle, or a collection of paths)
- Approach 1: solve using max flow (merging all points with the same angle into a single node with capacity = #points)
 - Time complexity with Ford-Fulkerson is $O(p^2)$ where p is the number of train lines adjacent to some remaining person.
 - **2** However p is hard to analyze. Turns out that $p \approx \max \text{ coordinate} = 1000$, so this approach is fast enough.

Problem

Given a set of rays from in 2D (0,0), and some points, assign max #points to a ray of minimum angular distance from the point, subject to ray capacities.

- For remaining points (having two closest rays) we get a bipartite matching problem between points and rays.
- **2** Graph is very simple (either a cycle, or a collection of paths)
- 3 Approach 2: greedyish solution

Problem

Given a set of rays from in 2D (0,0), and some points, assign max #points to a ray of minimum angular distance from the point, subject to ray capacities.

- For remaining points (having two closest rays) we get a bipartite matching problem between points and rays.
- **2** Graph is very simple (either a cycle, or a collection of paths)
- O Approach 2: greedyish solution
 - First cut the cycle anywhere to get a path, solve path with simple greedy

Problem

Given a set of rays from in 2D (0,0), and some points, assign max #points to a ray of minimum angular distance from the point, subject to ray capacities.

- For remaining points (having two closest rays) we get a bipartite matching problem between points and rays.
- **②** Graph is very simple (either a cycle, or a collection of paths)
- O Approach 2: greedyish solution
 - First cut the cycle anywhere to get a path, solve path with simple greedy
 - Make a second greedy pass to adjust assignment across the point where we cut the cycle.

Problem

Given a set of rays from in 2D (0,0), and some points, assign max #points to a ray of minimum angular distance from the point, subject to ray capacities.

- For remaining points (having two closest rays) we get a bipartite matching problem between points and rays.
- **②** Graph is very simple (either a cycle, or a collection of paths)
- 3 Approach 2: greedyish solution
 - First cut the cycle anywhere to get a path, solve path with simple greedy
 - Make a second greedy pass to adjust assignment across the point where we cut the cycle.
 - Time complexity is $O(n \log n)$.

Problem

Given a set of rays from in 2D (0,0), and some points, assign max #points to a ray of minimum angular distance from the point, subject to ray capacities.

Phase 2

- For remaining points (having two closest rays) we get a bipartite matching problem between points and rays.
- **②** Graph is very simple (either a cycle, or a collection of paths)
- O Approach 2: greedyish solution
 - First cut the cycle anywhere to get a path, solve path with simple greedy
 - Make a second greedy pass to adjust assignment across the point where we cut the cycle.
 - Time complexity is $O(n \log n)$.

Statistics: 17 submissions, 0 accepted

F — Fractal Tree

Problem

Given a huge tree with potentially 100000²³⁰ vertices, find distances between pairs of vertices.

Solution

 A copy of F₃₀ will have at least 2³⁰ vertices (assuming F₀ has at least 2 leaves)

F — Fractal Tree

Problem

Given a huge tree with potentially 100000²³⁰ vertices, find distances between pairs of vertices.

Solution

- A copy of F₃₀ will have at least 2³⁰ vertices (assuming F₀ has at least 2 leaves)
- 3 If k > 30, only relevant part is bottom-left copy of F_{30} and the path to this subtree.

F — Fractal Tree

Problem

Given a huge tree with potentially 100000²³⁰ vertices, find distances between pairs of vertices.

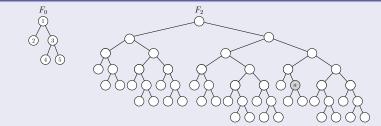
Solution

- A copy of F₃₀ will have at least 2³⁰ vertices (assuming F₀ has at least 2 leaves)
- 2 If k > 30, only relevant part is bottom-left copy of F_{30} and the path to this subtree.
- Reduces the problem to $k \leq 30$.

Problem

Given a huge tree with potentially 100000²³⁰ vertices, find distances between pairs of vertices.

Solution

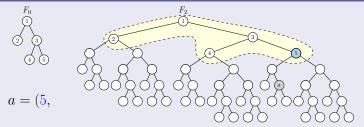


1 Representation of vertex *a* in the big tree:

Problem

Given a huge tree with potentially 100000²³⁰ vertices, find distances between pairs of vertices.

Solution



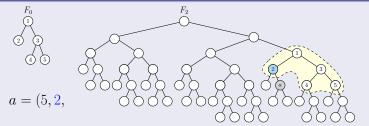
1 Representation of vertex *a* in the big tree:

• Record sequence $(a_1, a_2, ...)$ of leaves picked in each copy of F_0 when going from root to a

Problem

Given a huge tree with potentially 100000²³⁰ vertices, find distances between pairs of vertices.

Solution



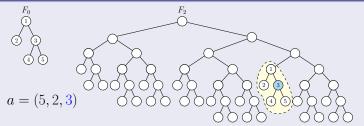
Representation of vertex a in the big tree:

• Record sequence $(a_1, a_2, ...)$ of leaves picked in each copy of F_0 when going from root to a

Problem

Given a huge tree with potentially 100000²³⁰ vertices, find distances between pairs of vertices.

Solution



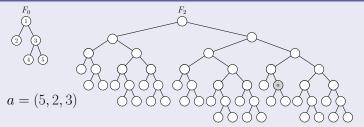
Representation of vertex a in the big tree:

- Record sequence $(a_1, a_2, ...)$ of leaves picked in each copy of F_0 when going from root to a
- **②** Finally add which node a corresponds to in last copy of F_0 .

Problem

Given a huge tree with potentially 100000²³⁰ vertices, find distances between pairs of vertices.

Solution



- Representation of vertex a in the big tree.
- Can find this representation in O(k log n) time using binary search and precomputation of subtree sizes.

Problem

Given a huge tree with potentially 100000²³⁰ vertices, find distances between pairs of vertices.

Solution

• What is distance between (a_1, \ldots, a_p) and (b_1, \ldots, b_q) ?

Problem

Given a huge tree with potentially 100000²³⁰ vertices, find distances between pairs of vertices.

Solution

- What is distance between (a_1, \ldots, a_p) and (b_1, \ldots, b_q) ?
- First remove any common prefix (moving into the same subtree does not affect distance)

Problem

Given a huge tree with potentially 100000²³⁰ vertices, find distances between pairs of vertices.

Solution

- What is distance between (a_1, \ldots, a_p) and (b_1, \ldots, b_q) ?
- First remove any common prefix (moving into the same subtree does not affect distance)

$${f 0}$$
 Then, when $a_1
eq b_1$, distance is

$$d(a_1, b_1) + \sum_{i=2}^{p} h(a_i) + \sum_{i=2}^{q} h(b_i)$$

 d(a₁, b₁) = distance between a₁ and b₁ in F₀ (can compute it using a lowest common ancestor (LCA) algorithm)
 h(x) = depth of node x in F₀

Problem

Given a huge tree with potentially 100000²³⁰ vertices, find distances between pairs of vertices.

Solution

- What is distance between (a_1, \ldots, a_p) and (b_1, \ldots, b_q) ?
- First remove any common prefix (moving into the same subtree does not affect distance)

$${f 0}$$
 Then, when $a_1
eq b_1$, distance is

$$d(a_1, b_1) + \sum_{i=2}^{p} h(a_i) + \sum_{i=2}^{q} h(b_i)$$

 d(a₁, b₁) = distance between a₁ and b₁ in F₀ (can compute it using a lowest common ancestor (LCA) algorithm)
 h(x) = depth of node x in F₀

Statistics: 5 submissions, 0 accepted

Random numbers

- 253 teams
- 611 contestants
- 2819 total number of submissions

10 programming languages used by teams

Ordered by #submissions: C++ (1016), Java (865), Python (763), C (67), C# (65), Haskell (16), Prolog (9), Scala (8), Go (6), Ruby (4)

438 number of lines of code used in total by the shortest jury solutions to solve the entire problem set.
(Significantly smaller than previous years - no killer problem in terms of implementation this year.)

• All but two of the problems have **near-linear solutions** Exceptions:

- All but two of the problems have **near-linear solutions** Exceptions:
 - D (Distinctive Character) $O(n + k \cdot 2^k)$ solution
 - $| (Import Spaghetti) O(n^3)$ solution.

- All but two of the problems have **near-linear solutions** Exceptions:
 - D (Distinctive Character) $O(n + k \cdot 2^k)$ solution | (Import Spaghetti) – $O(n^3)$ solution.
- Two weeks ago, 3 people had written solutions to H (Hubtown). A day later, it had turned out that the 3 solutions were all wrong, with 3 completely different bugs, and that the test case generator had also been buggy.

- All but two of the problems have **near-linear solutions** Exceptions:
 - D (Distinctive Character) $O(n + k \cdot 2^k)$ solution | (Import Spaghetti) – $O(n^3)$ solution.
- Two weeks ago, 3 people had written solutions to H
 (Hubtown). A day later, it had turned out that the 3
 solutions were all wrong, with 3 completely different bugs, and
 that the test case generator had also been buggy.
 Two days ago, one of those Hubtown solutions again turned
 out to be wrong, more data was added.

- All but two of the problems have **near-linear solutions** Exceptions:
 - D (Distinctive Character) $O(n + k \cdot 2^k)$ solution | (Import Spaghetti) – $O(n^3)$ solution.
- Two weeks ago, 3 people had written solutions to H
 (Hubtown). A day later, it had turned out that the 3
 solutions were all wrong, with 3 completely different bugs, and
 that the test case generator had also been buggy.
 Two days ago, one of those Hubtown solutions again turned
 out to be wrong, more data was added.
- The jury wrote Python solutions for all problems except C (Compass Card Sales). But mostly in Python 2, which is faster than Python 3 on Kattis due to using pypy instead of CPython. The Python solutions are always the shortest (often by a wide margin).

 Northwestern Europe Regional Contest (NWERC): November 26 in Bath (UK). Teams from Nordic, Benelux, Germany, UK, Ireland.



• Each university sends up to two teams to NWERC to fight for spot in World Finals (April 2018, in Beijing, China)